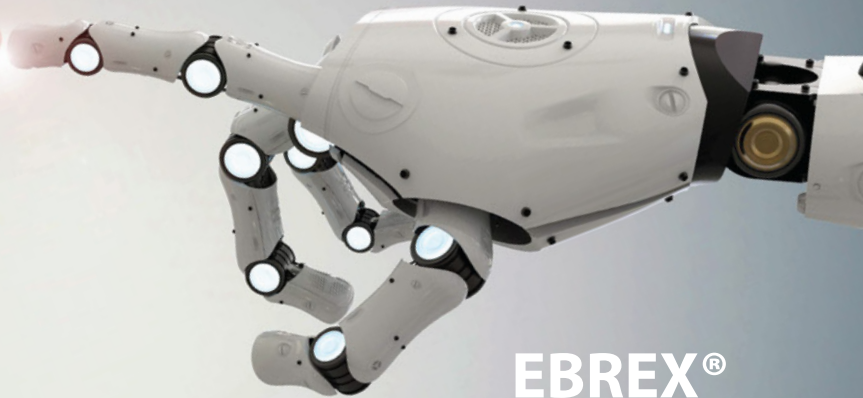
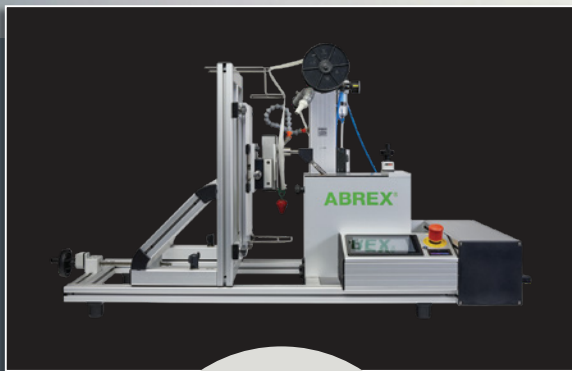


# HUMAN TOUCH VS. ROBOT TOUCH



ABREX®



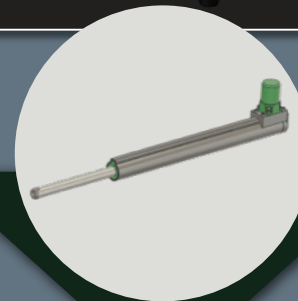
Human Fingertip Touch Simulation  
with Pneumatic Drive System

Provide dynamic, non-linear movement

99% simulation providing the same  
wear pattern as the one from the field

Feasible air-blow function to avoid  
unnecessary abrasive

EBREX®



Robot Finger Touch Simulation with  
non-Pneumatic Drive System

Provide linear and constant speed

Perform tribological material testing

Provide high speed performance

No air supply required